

# Differential Evolution for Self-adaptive Triangular Brushstrokes

Uroš Mlakar, Janez Brest, Aleš Zamuda

University of Maribor

*{uros.mlakar,janez.brest,ales.zamuda}@um.si*

Student Workshop on Bioinspired Optimization Methods  
and their Applications (BIOMA 2014)

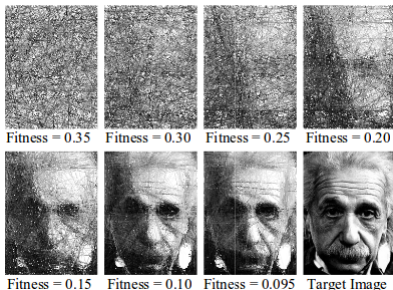
13th International Conference on  
Parallel Problem Solving from Nature (PPSN 2014)

Ljubljana, Slovenia, September 13, 2014

- 1 Motivation and Related Work
- 2 Differential Evolution
- 3 The Proposed Method
  - Encoding
  - Genotype  $\rightarrow$  Phenotype Rendering
  - Fitness Evaluation
- 4 Results
- 5 Conclusion

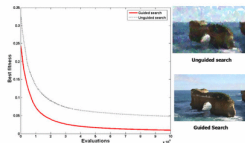
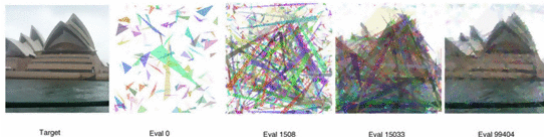
# Motivation: Line Strokes

- Riley et al. (WCCI Barcelona, July 2010) compared 2 representations
  - variable-length classic genetic algorithm and
  - tree-based genetic algorithm.
- Line strokes to generate evolved images
  - best fitness was  $\sim 9.4\%$  of the original image,
  - using a tree-based algorithm.



# Motivation: Triangular Brushstrokes

- Izadi et al. (AJCAI, Adelaide, December 2010) used GP for the creation of non-photorealistic animations
  - unguided and guided searches: the guided yields better results,
  - filled and empty brushstrokes,
  - reported results are:
    - unguided:  $\sim 5\%$
    - guided:  $\sim 2\%$  - requires the source image in the phenotype rendering.



# Differential Evolution (DE)

- A floating-point encoding EA for global optimization over continuous spaces,
  - through **generations**,  
**the evolution process** improves **population of vectors**,
  - iteratively by combining a parent individual and several other individuals of the same population.
- We choose the **strategy** *jDE/rand/1/bin*
  - **mutation**:  $\mathbf{v}_{i,G+1} = \mathbf{x}_{r_1,G} + F \times (\mathbf{x}_{r_2,G} - \mathbf{x}_{r_3,G})$ ,
  - **crossover**: 
$$u_{i,j,G+1} = \begin{cases} v_{i,j,G+1} & \text{if } \text{rand}(0, 1) \leq CR \text{ or } j = j_{rand} \\ x_{i,j,G} & \text{otherwise} \end{cases},$$
  - **selection**: 
$$\mathbf{x}_{i,G+1} = \begin{cases} \mathbf{u}_{i,G+1} & \text{if } f(\mathbf{u}_{i,G+1}) < f(\mathbf{x}_{i,G}) \\ \mathbf{x}_{i,G} & \text{otherwise} \end{cases},$$
  - includes mechanism of  $F$  and  $CR$  control parameters self-adaptation.

# The Proposed Method (Encoding)

- An individual encoded image is stored into a DE vector:  
 $\mathbf{x} = (x_1, x_2, \dots, x_{8T^{max}}, F, CR, T^L, T^U)$ , size is  $D + 4$ ,  $D = 8T^{max}$ ,
- the scaling factor  $F$  and crossover rate  $CR$  as used by the jDE,
- then  $T^L$  and  $T^U$  follow.
- The parameters  $T^L$  and  $T^U$  define the number of triangles  $T_i$ :
  - $T_i$  rendered in the evolved image,
  - $T^L$  and  $T^U$  updated similarly as the  $F$  control parameter.

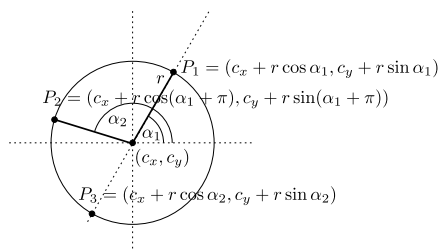
# The Proposed Method (Genotype $\rightarrow$ Phenotype Rendering) 1/3

- DE vector  $\mathbf{x}_i, \forall i \in \{1, \dots, NP\}$  constituting a genotype rendered into a phenotype image  $\mathbf{z}_i$  (to be compared against  $\mathbf{z}^*$ ).
- Each brushstroke is represented as  $(c_x, c_y, r, \alpha_1, \alpha_2, b^Y, b^{Cb}, b^{Cr})$ :  
$$c_x \in [0, \dots, R_x), \quad c_y \in [0, \dots, R_y), \quad r \in \left[0, \frac{R_x}{\sqrt{T_{max}}}\right), \quad \alpha_1 \in [0^\circ, 360^\circ),$$
$$\alpha_2 \in [0^\circ, 180^\circ), \quad b^Y \in [16, 236), \quad b^{Cb} \in [16, 241), \quad b^{Cr} \in [16, 241).$$
- $c_x$  and  $c_y$  define the center of the triangle to be rendered,
- $r$  defines its circumscribed circle,
- $\alpha_1, \alpha_2$  define the points of the triangle on the circumscribed triangle,
- $b^Y, b^{Cb}, b^{Cr}$  are the color components of its brush.

# The Proposed Method (Genotype $\rightarrow$ Phenotype Rendering) 2/3

- The triangle vertices encoded by  $\mathbf{x}_i$  construct  $T_i$  triangles,
- each triangle  $\mathbf{T}_k = (c_x, c_y, r, \alpha_1, \alpha_2)$  defines vertices as in Figure on the right, Eq. 1.
- For optimization, the **YCbCr** color space is used.
- For rendering, the brush color  $\mathbf{b}_k^{YCbCr}$  is transformed to the RGB color space using the Eq. 2.

Figure: Triangle brush definition



Eq. 1

$$P_{1,k} = \lfloor (c_{x,k} + r_k \cos \alpha_{1,k}, c_{y,k} + r_k \sin \alpha_{1,k}) \rfloor$$
$$P_{2,k} = \lfloor (c_{x,k} + r_k \cos(\alpha_{1,k} + \pi), c_{y,k} + r_k \sin(\alpha_{1,k} + \pi)) \rfloor$$
$$P_{3,k} = \lfloor (c_{x,k} + r_k \cos \alpha_{2,k}, c_{y,k} + r_k \sin \alpha_{2,k}) \rfloor$$

Eq. 2

$$b_k^R = \lfloor 1.164(b_k^Y - 16) + 1.596(b_k^{Cr} - 128) \rfloor$$
$$b_k^G = \lfloor 1.164(b_k^Y - 16) - 0.813(b_k^{Cr} - 128) - 0.391(b_k^{Cb} - 128) \rfloor$$
$$b_k^B = \lfloor 1.164(b_k^Y - 16) + 2.018(b_k^{Cb} - 128) \rfloor$$



# The Proposed Method (Genotype $\rightarrow$ Phenotype Rendering) 3/3

- For each triangle  $T_k$ , a solid color is rendered,
- over the brush area with a transparency factor  $\frac{1}{T_i}$ ,
- which makes the color of the brush:  $\mathbf{b}_k = \lfloor \frac{255}{T_i} \mathbf{b}_{RGB}^k \rfloor$ ;
- this is analogous to blending each triangle as part-transparent triangle withing the evolved image:
  - $\mathbf{z}_{x,y}^k = \sum_{T_k \text{ over}(x,y)} \lfloor \frac{255}{T_i} \mathbf{b}_{k,x,y}^{RGB} \rfloor$ .
- Triangles defined over the edges of the image canvas are drawn by clipping away pixels outside of the canvas area.

- After a phenotype image  $\mathbf{z}_i$  is rendered: it is compared to a reference image  $\mathbf{z}^*$ 
  - using the evaluation metric:

$$f(\mathbf{z}) = 100 \times \frac{\sum_{y=0}^{R_y-1} \sum_{x=0}^{R_x-1} |z_{x,y}^{*R} - z_{x,y}^R| + |z_{x,y}^{*G} - z_{x,y}^G| + |z_{x,y}^{*B} - z_{x,y}^B|}{3 \times 255 \times R_x R_y}.$$

- The obtained result is the similarity of the evolved image and the reference image.
- The goal of the evolutionary process is to minimize the function value  $f(\mathbf{z})$ .

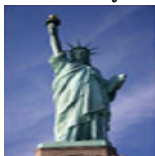
# Results (Experimental Setup)

- The parameter sets are:
  - $NP = \{25, 50, 100\}$ ,
  - $T_{max} = \{10, 20, \dots, 150\}$ ,
  - $RN_i = \{0, 1, \dots, 51\}$ ,
  - $MAXFES = 1e+5$ .
- A total of 45 parameter settings, 2340 independent runs.
- Rendering: GDI+.
- The experiments conducted on 4 images of size  $100 \times 100$  pixels.
- Additional experiment: all images evolved up to  $MAXFES = 1e+6$ .

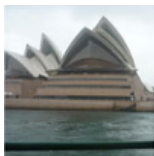
Baboon



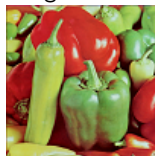
Liberty



Palace



Vegetables



# Results (Experiment)

Best fitness values for all parameter sets for all images,  $MAXFES = 1e+5$

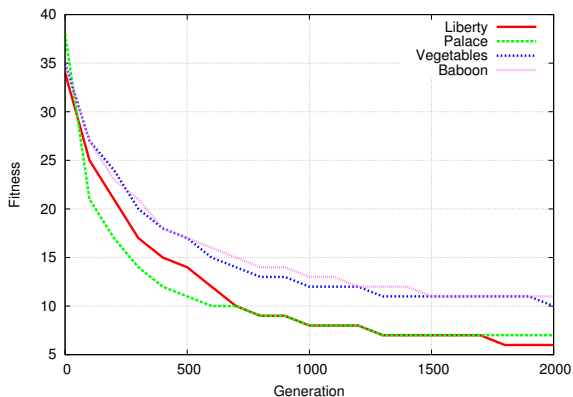
Table 1. Obtained fitness over  $T_{max}$  and  $NP$ : test instances Liberty and Palace.

$NP$ $T_{max}$	Liberty				Palace			
	Best	Worst	Average	STD	Best	Worst	Average	STD
25 10	8.29	11.99	9.93096	0.8233	8.69	13.69	10.1362	0.9655
25 20	8.03	13.14	10.0935	1.0845	7.83	11.5	9.12173	0.8092
25 30	8.41	13.74	10.0525	1.1712	7.52	11.1	8.97942	0.7992
25 40	8.13	12.81	10.4408	1.1416	7.34	11.36	8.91788	0.8922
25 50	8.49	13.37	10.6767	1.1768	7.65	12.53	8.87442	0.9788
25 60	7.95	14.65	10.9858	1.4284	7.9	11.88	8.99673	0.8761
25 70	8.28	14.21	11.4075	1.3630	7.79	13.17	9.50327	1.0482
25 80	8.72	15.89	11.7554	1.6330	7.97	12.34	9.43558	0.9765
25 90	8.84	16.24	12.1342	1.6608	8.41	13.54	9.82	1.2756
25 100	9.01	16.74	12.4798	1.7521	8.62	12.96	9.83635	0.8869
25 110	8.07	16.78	12.7412	1.7849	9.01	14.42	10.4119	1.2468
25 120	9.67	16.14	12.8467	1.7359	8.93	15.13	10.3858	1.3149
25 130	10.16	17.96	13.2692	1.7193	9.02	14.2	10.2858	1.0292
25 140	9.29	17.99	13.7029	1.7886	8.29	13.51	10.7779	1.0299
25 150	10.82	18.56	14.0373	1.6573	9.89	14.91	11.1206	1.0586
50 10	7.51	9.69	8.45077	0.4198	7.43	11.84	8.68058	0.8825
50 20	6.78	8.99	7.80173	0.4987	<b>7.1</b>	11.39	8.79173	0.9592
50 30	6.89	9.17	7.81788	0.5119	7.53	12.58	9.75654	1.1186
50 40	<b>6.77</b>	9.87	8.0375	0.6578	8.27	12.24	10.0575	0.9537
50 50	7.08	10.61	8.39923	0.7056	7.99	13.14	10.3338	1.1009
50 60	7.15	10.4	8.67115	0.7472	8.59	12.49	10.7817	1.0754
50 70	7.46	10.9	9.1025	0.8606	7.58	12.8	10.7744	1.1086
50 80	7.6	11.4	9.47981	0.8689	9.15	13.11	11.3802	1.0178
50 90	8.05	12.65	9.67346	0.9115	9.97	13.41	11.5227	0.9315
50 100	8.75	11.75	10.0152	0.7824	8.55	13.62	11.4356	0.9923
50 110	8.93	13.63	10.6356	0.9682	9.32	13.77	12.0712	0.9579
50 120	9.22	13.01	10.7502	0.9840	9.77	14.21	12.429	0.8972
50 130	9.42	12.59	11.0527	0.7707	11.37	14.07	12.7387	0.6134
50 140	9.99	13.39	11.5719	0.7815	9.69	15.5	12.9317	0.9708
50 150	10.2	14.56	12.2633	1.0702	9.58	15.36	12.8092	1.1717
100 10	7.1	9.12	7.98596	0.4241	7.91	13.88	10.9573	1.8019
100 20	6.85	9.77	7.83962	0.5360	8.86	14.59	12.1117	1.2862
100 30	7.15	11.8	8.49077	1.1563	9.59	16.15	12.9698	1.0589
100 40	7.22	13	8.86327	1.1092	9.65	14.97	13.2177	1.1543
100 50	7.41	12.75	9.34846	1.3939	11.01	15.52	13.8060	0.9750
100 60	8.06	12.97	9.77731	1.1539	11.05	16.14	14.8156	1.1234
100 70	8.67	13.28	10.1954	1.3722	10.77	16.32	14.3629	1.1713
100 80	8.73	14.48	11.0929	1.4093	10.98	17.06	14.9348	1.1679
100 90	9.04	14.92	11.3594	1.3483	11.1	16.8	15.104	1.2586
100 100	9.4	16.13	11.6604	1.4952	10.8	17.62	15.36	1.2330
100 110	10.17	15.68	12.3365	1.5685	13.01	17.86	16.0202	0.9744
100 120	10.26	15.45	12.3358	1.5076	11.07	17.99	15.6113	1.6455
100 130	10.22	16.19	13.2212	1.6108	12.33	18.37	16.4085	1.3168
100 140	11.42	16.65	13.7808	1.5502	11.64	18.35	16.1229	1.4990
100 150	11.35	18.68	14.6113	1.9720	10.11	18.34	16.2929	2.0056

Table 2. Obtained fitness over  $T_{max}$  and  $NP$ : test instances Vegetables and Baboon.

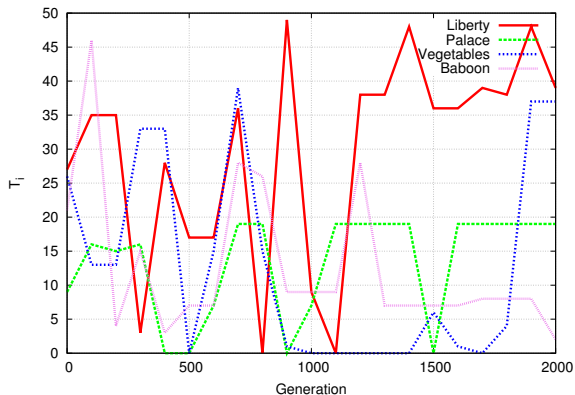
$NP$ $T_{max}$	Vegetables				Baboon			
	Best	Worst	Average	STD	Best	Worst	Average	STD
25 10	14.13	17.21	15.7269	0.7148	15.02	18.59	16.38	0.7128
25 20	12.56	18.03	15.9558	0.9850	13.44	17.12	15.3815	0.8129
25 30	12.33	15.98	13.9215	0.8475	12.99	19.03	15.0204	1.1150
25 40	11.62	16.21	13.674	1.0436	11.99	16.85	14.542	1.0135
25 50	12.16	17.08	13.88	1.0726	11.39	17.62	14.4573	1.2299
25 60	11.64	17.88	13.6438	1.2155	11.74	17.51	14.8038	1.2229
25 70	11.29	17.15	13.9056	1.3790	11.88	17.9	14.6267	1.3495
25 80	11.61	16.6	14.0871	1.3881	12.11	17.13	14.3606	1.2815
25 90	11.63	17.96	14.1062	1.4428	11.93	19.41	14.6644	1.5269
25 100	11.34	17	14.4533	1.4694	11.7	18.77	14.7642	1.7438
25 110	11.74	19.66	14.6085	1.7664	12.02	19.11	15.0006	1.6708
25 120	12.26	17.91	14.7737	1.5726	12.2	18.5	15.6467	1.6086
25 130	12.1	19.75	14.6338	1.9283	13.01	19.5	15.4254	1.5505
25 140	11.94	19.01	14.7835	1.6282	12.64	19.37	15.8235	1.8458
25 150	12.82	18.7	14.6487	1.3015	13.13	20.17	15.7952	1.6923
50 10	13.03	15	14.0723	0.4674	13.86	16.52	14.9192	0.5494
50 20	11.66	13.26	12.4644	0.3184	11.8	14.54	13.271	0.5569
50 30	11.12	13.59	12.2425	0.6528	11.59	13.62	12.5706	0.5732
50 40	<b>10.94</b>	14.1	12.1848	0.6656	11.1	13.84	12.3137	0.6090
50 50	11.04	13.92	12.2946	0.7009	11.34	14.36	12.4075	0.6304
50 60	11.29	15.86	12.5506	0.9222	11.25	14.1	12.3602	0.6161
50 70	11.18	15.21	12.6104	0.8682	11.54	14.57	12.5437	0.6510
50 80	11.32	15.26	12.8619	0.7658	<b>11.07</b>	15.56	12.9473	0.8087
50 90	11.84	15.28	13.0677	0.8038	11.37	16.2	12.8572	1.0291
50 100	11.79	15.8	13.5058	0.9565	11.85	15.72	13.2658	0.7972
50 110	12.02	15.92	13.5204	0.8750	11.98	15.56	13.4275	0.7805
50 120	11.9	16.87	13.829	1.1151	12.43	16.43	15.6106	0.7265
50 130	12.51	15.97	14.094	0.8855	12.64	16.32	14.085	0.8259
50 140	12.16	17.07	14.8198	1.2154	12.54	16.31	14.15	0.8865
50 150	13.11	17.98	14.9838	1.2072	13.08	18	14.8765	1.0178
100 10	12.56	16.19	13.9815	0.8083	13.49	16.19	14.5607	0.5672
100 20	11.84	16.45	13.4704	1.0483	12.02	15.87	13.7204	0.8747
100 30	11.83	17.64	13.9133	1.3335	12	15.76	13.8266	0.9727
100 40	12.01	17.95	14.6354	1.3660	11.63	17.01	13.6467	1.3582
100 50	11.87	17.35	14.9156	1.4272	11.99	17.48	14.1658	1.5554
100 60	12.92	18	15.21	1.5119	12.12	17.46	14.5921	1.4517
100 70	12.13	18.05	15.6513	1.2457	12.12	17.16	14.3881	1.3782
100 80	12.9	17.9	15.6008	1.4212	12.13	17.56	14.8656	1.4214
100 90	12.32	20.04	16.3233	1.7789	12.25	18.66	15.2598	1.5144
100 100	12.98	20.55	16.7275	1.7119	13.09	18.42	15.5958	1.5064
100 110	13.76	20.18	17.2896	1.5242	13	19.62	15.84	1.6164
100 120	13.12	20.62	17.626	1.5807	13.34	19.58	16.4725	1.5223
100 130	13.52	20.12	17.9052	1.3516	13.84	19.6	16.9367	1.7362
100 140	14.08	20.52	18.216	1.6975	14.3	21	17.4387	1.7372
100 150	14.97	21.19	19.1221	1.2128	14.75	21.13	17.9488	1.6872

# Results (Fitness Convergence Graph)



The fitness convergence graph of the best runs for all images.

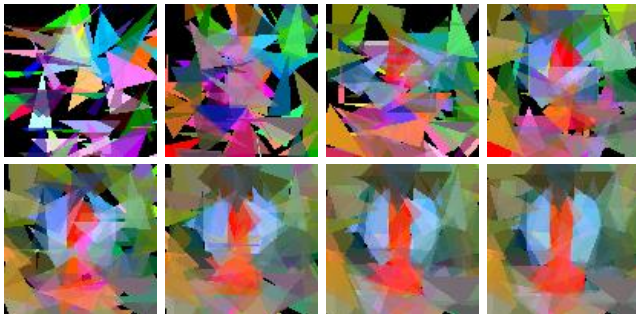
# Results ( $T_i$ Dynamics Graph)



The dynamics of the number of triangular brushstrokes in the best vectors.

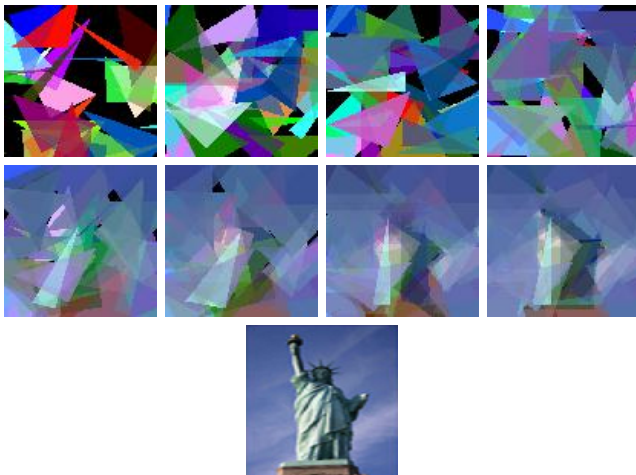
# Results (Image: Baboon)

Baboon



# Results (Image: Liberty)

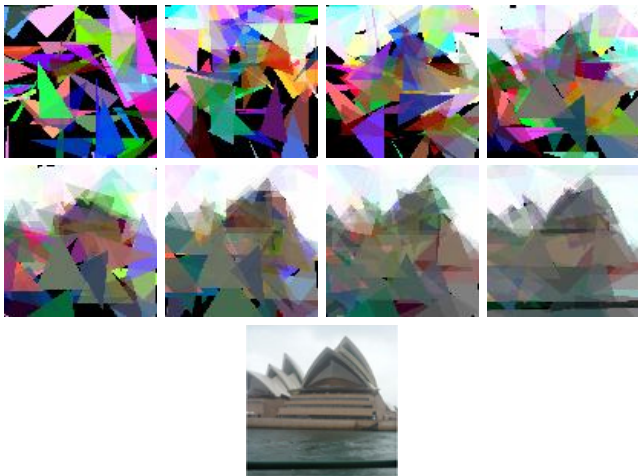
Liberty





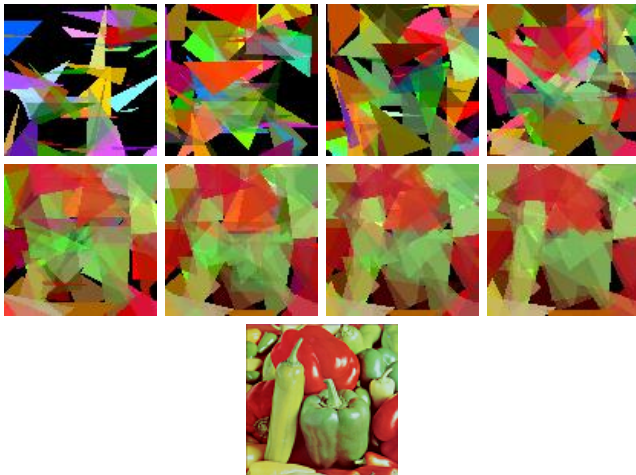
# Results (Image: Palace)

Palace



# Results (Image: Vegetables)

## Vegetables



- An evolvable lossy image representation using a jDE algorithm.
- The performance of this encoding: competitive with the GA tree representation.
- Experiments show promising results on sample images.
- In the future we would like to address:
  - different evolutionary operators,
  - change control-parameters updating, and
  - testing on more images with different properties.

# Thank you.



# Questions?