



# Extended Finite-State Machine Inference with Parallel Ant Colony Based Algorithms



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# Motivation: Reliable software

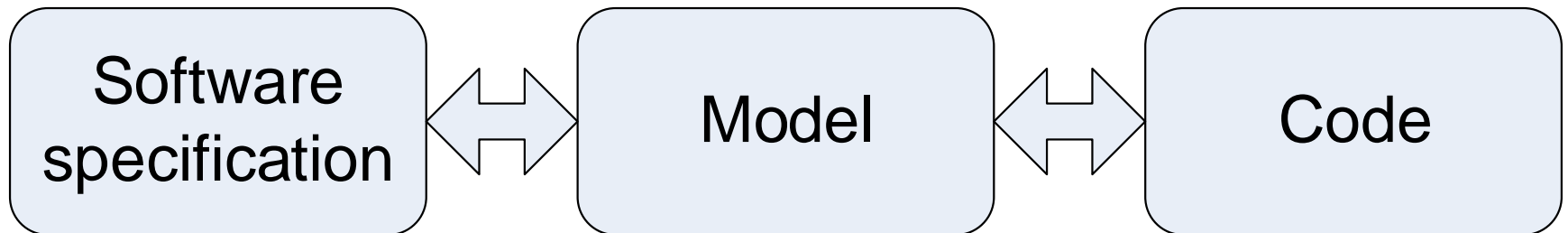
- Systems with high cost of failure
  - Energetics
  - Aerospace
  - Finances
  - ...
- We want to have **reliable software**
  - Testing is not enough
  - **Verification** is needed

# Challenge

- Reliable systems are hard to develop
- Verification is time consuming

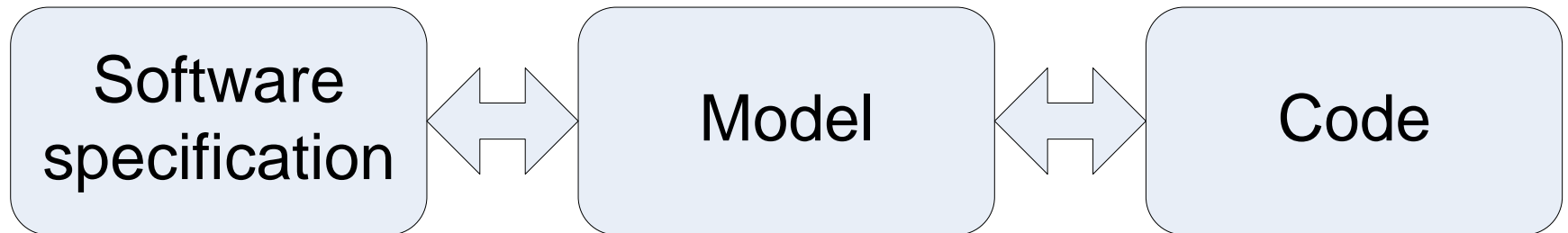
# Model-driven development

- Automated software engineering
- Model-driven development

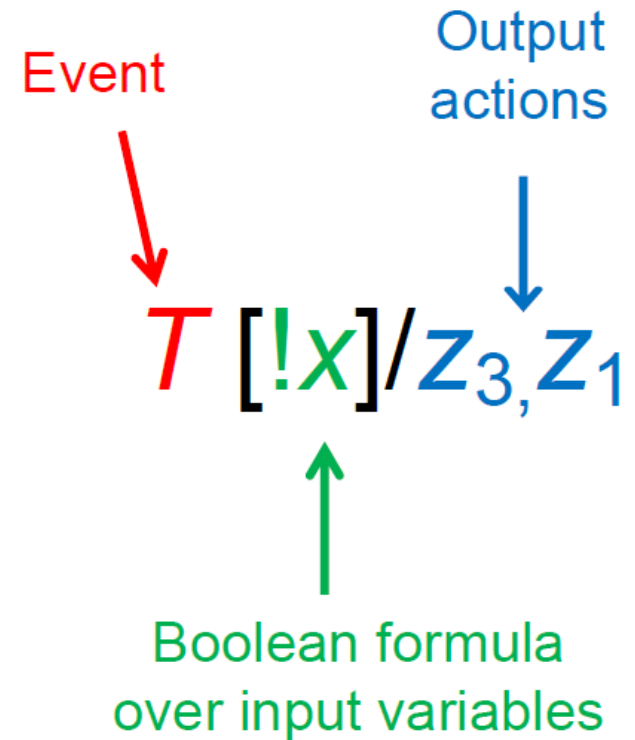
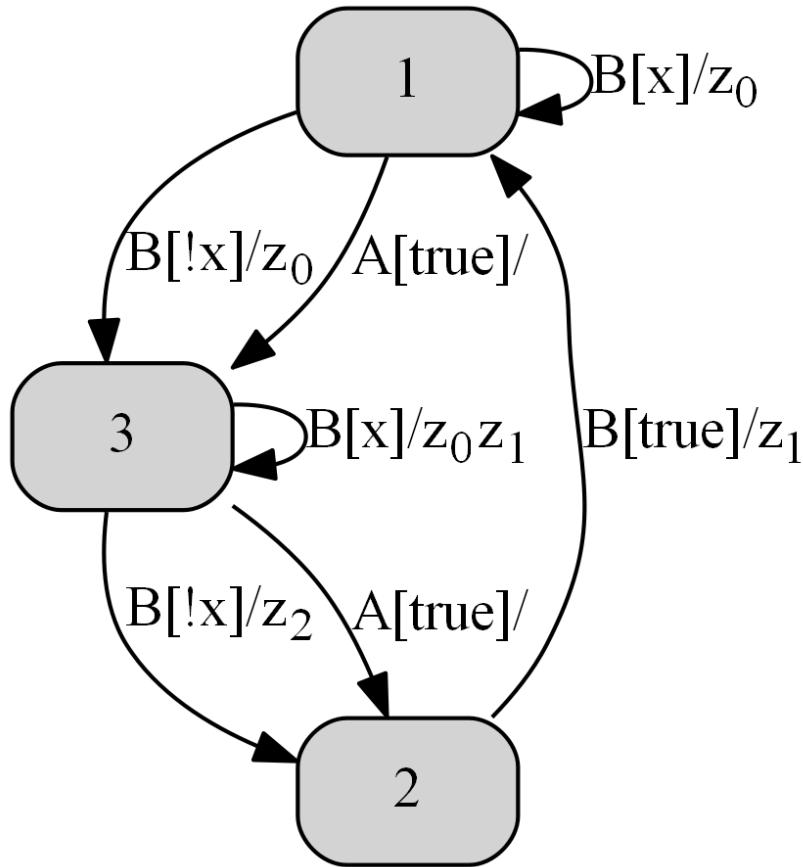


# Automata-based programming

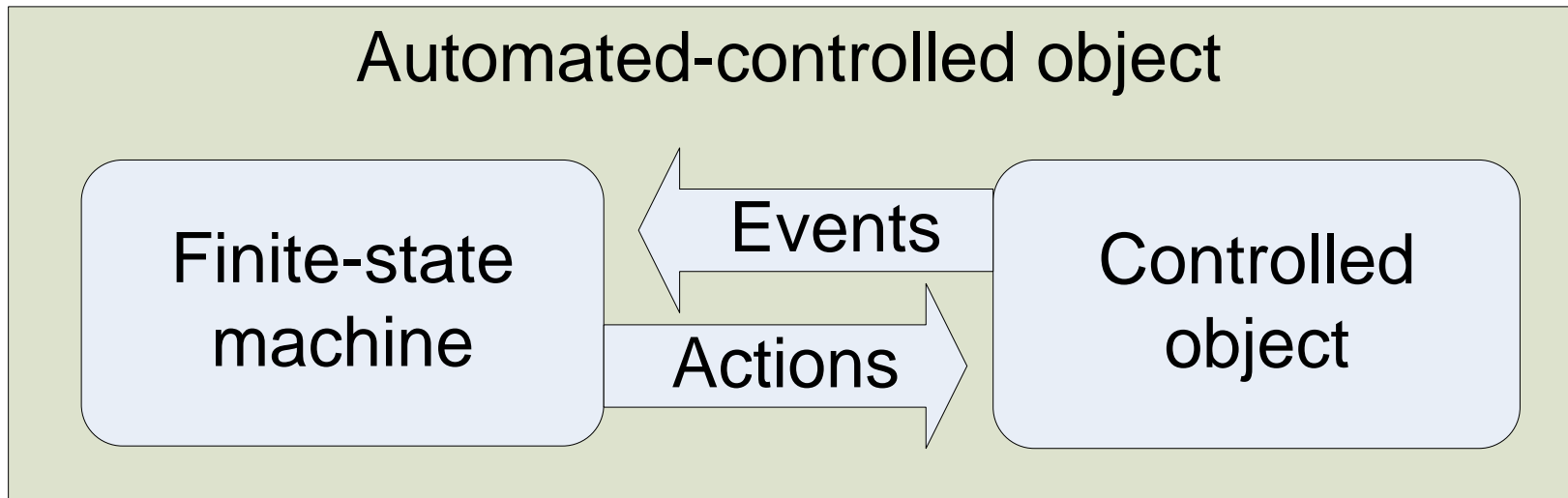
Extended  
Finite-state  
machine



# Extended Finite-State Machine



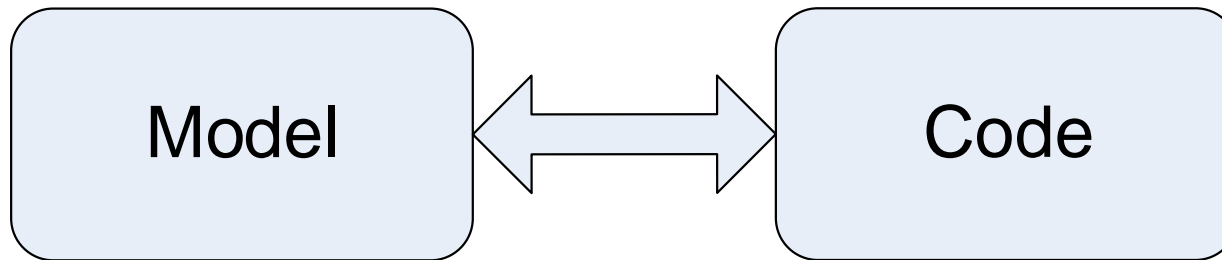
# Automata-based programming



# Automata-based programming: advantages

- Model before programming code, not vice versa

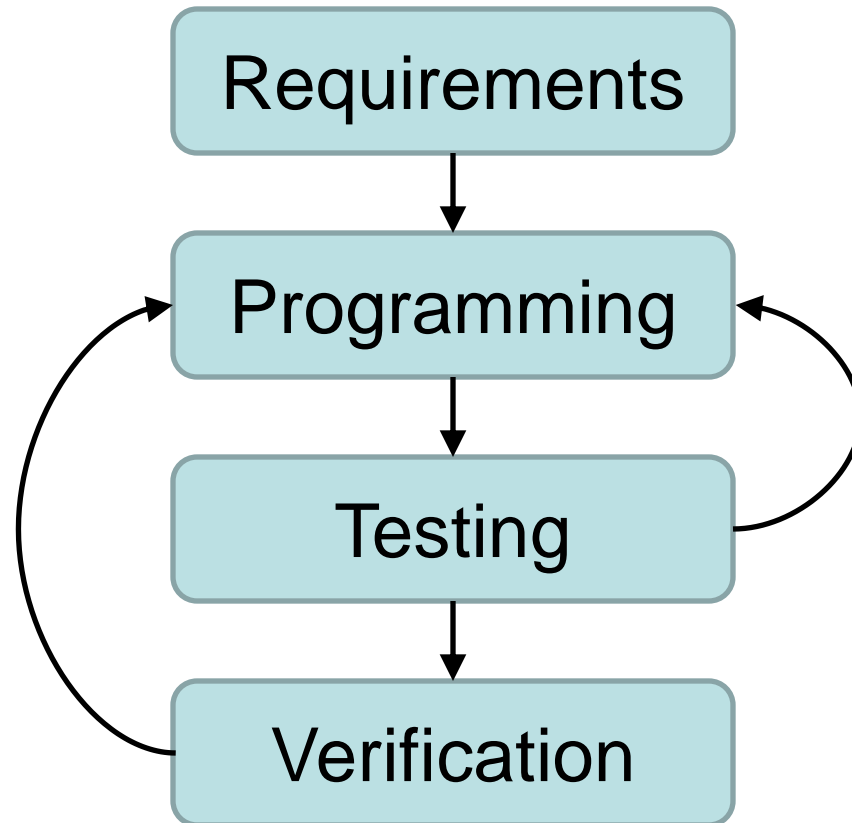
Finite-state machine



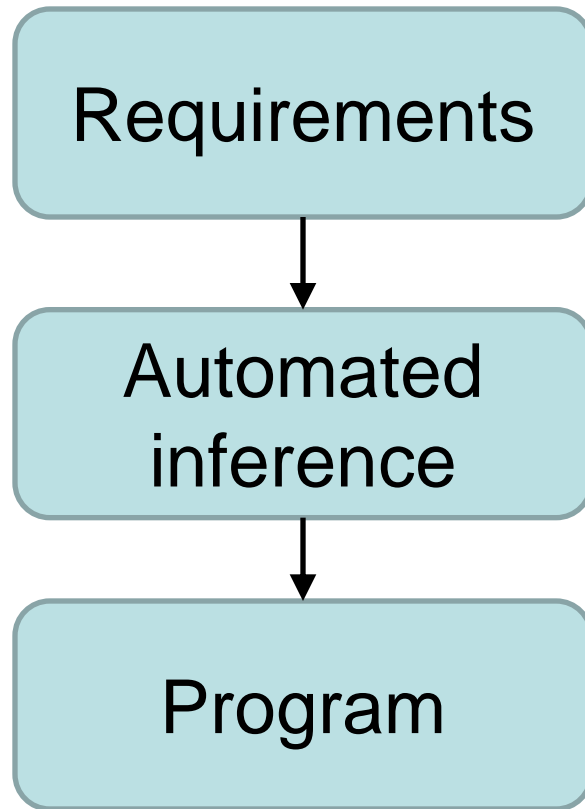
- Possibility of program verification using *Model Checking*



# Conventional workflow



# Automata-based programming workflow



- ✓ Easy for the user
- ✓ Time-consuming for computer

# Issues

- Hard to build an EFSM with desired behavior
- Sometimes, several hours on a single machine
- Use parallel algorithms

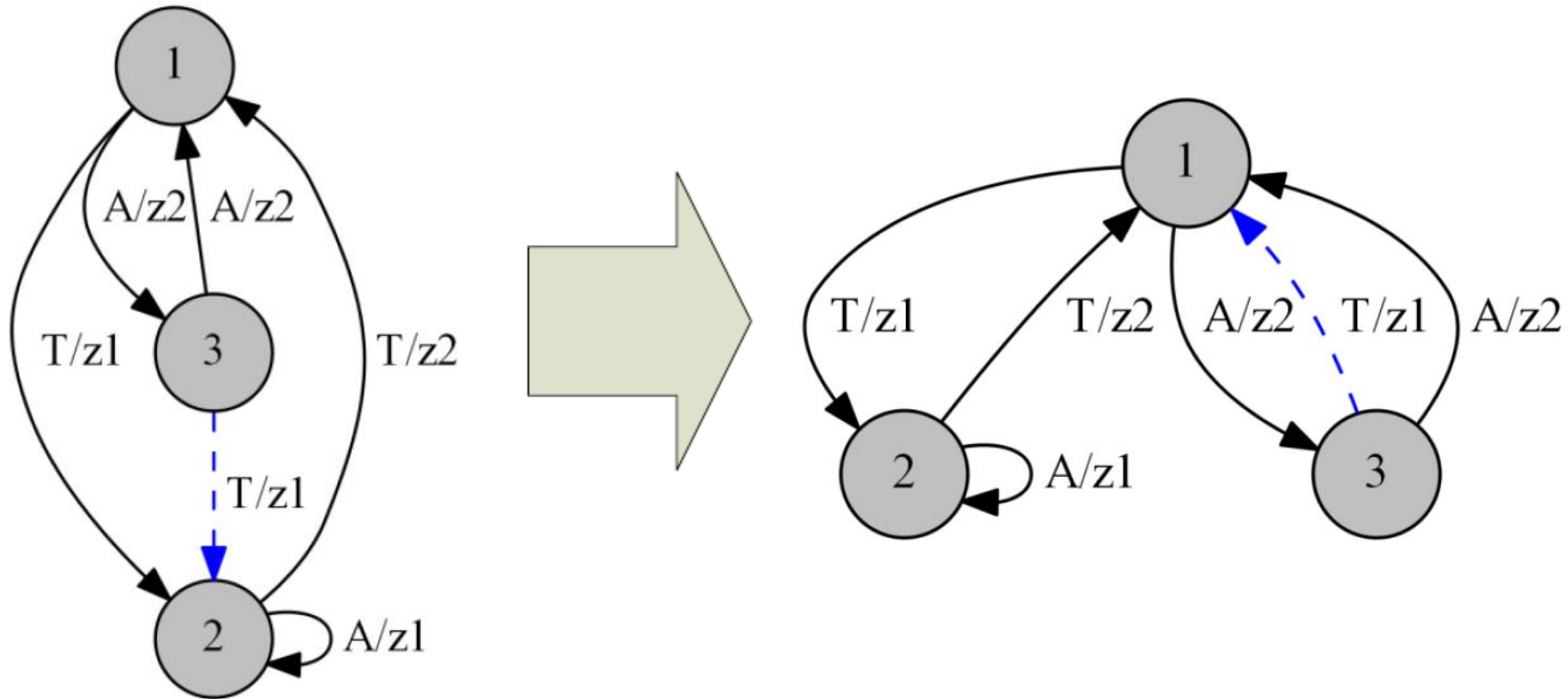
# EFSM inference algorithms

- Genetic algorithm (GA)
- Previous work: Mutation-based Ant Colony Optimization (MuACO)
- ...
- No parallel implementations so far

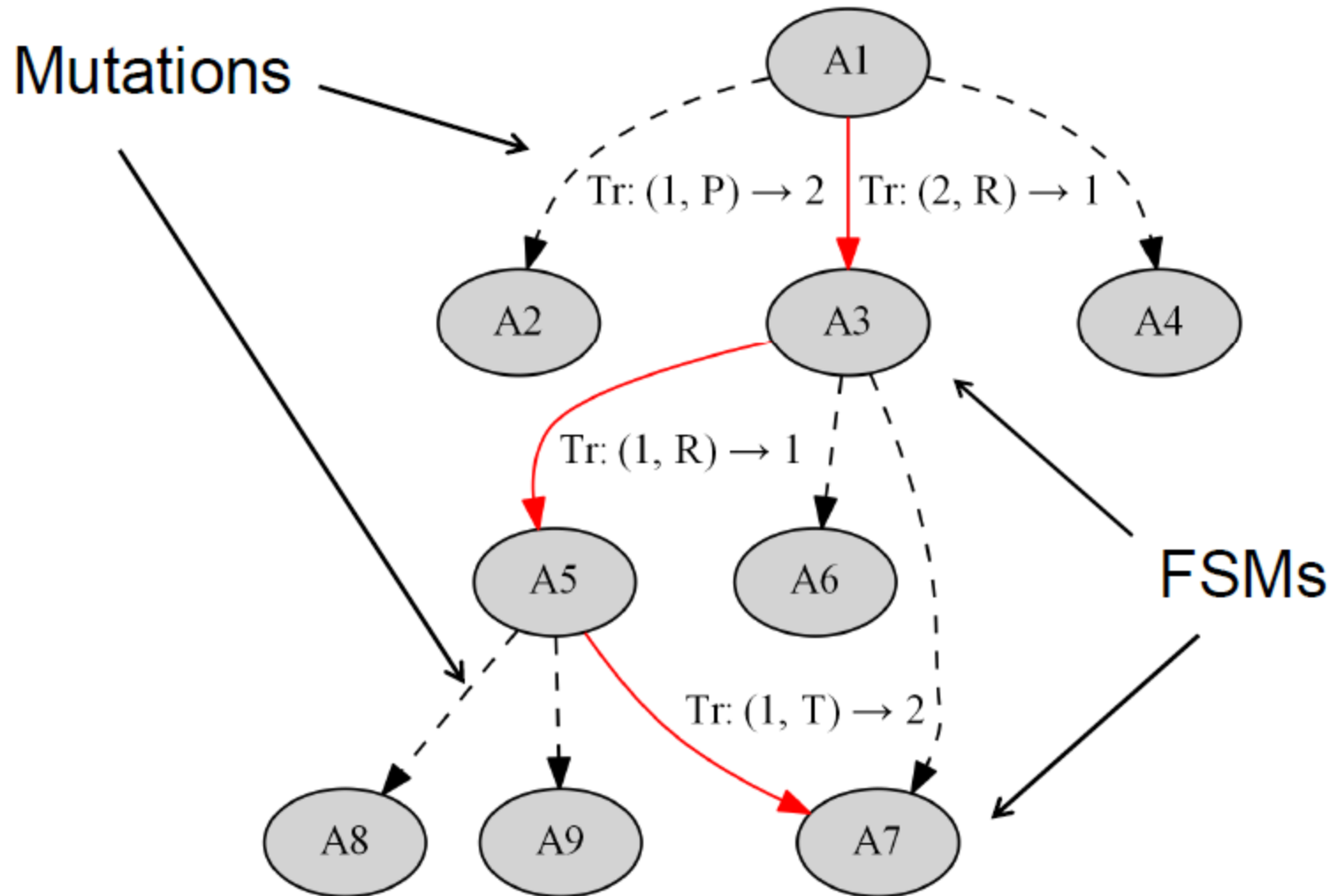
# In this work

- Develop several parallel versions of MuACO
- Compare
  - With each other
  - With parallel GA
  - Statistical significance

# EFSM mutations



# MuACO algorithm



# MuACO algorithm

$A_0 = \text{random FSM}$

Graph =  $\{A_0\}$

while not stop() do

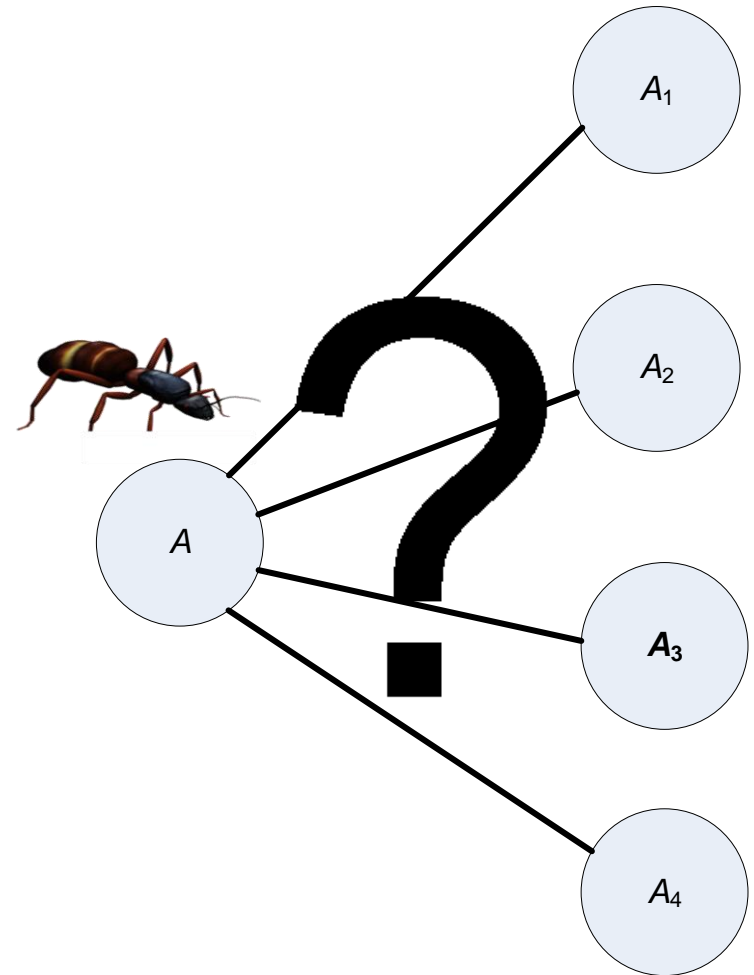
    ConstructAntSolutions

    UpdatePheromoneValues

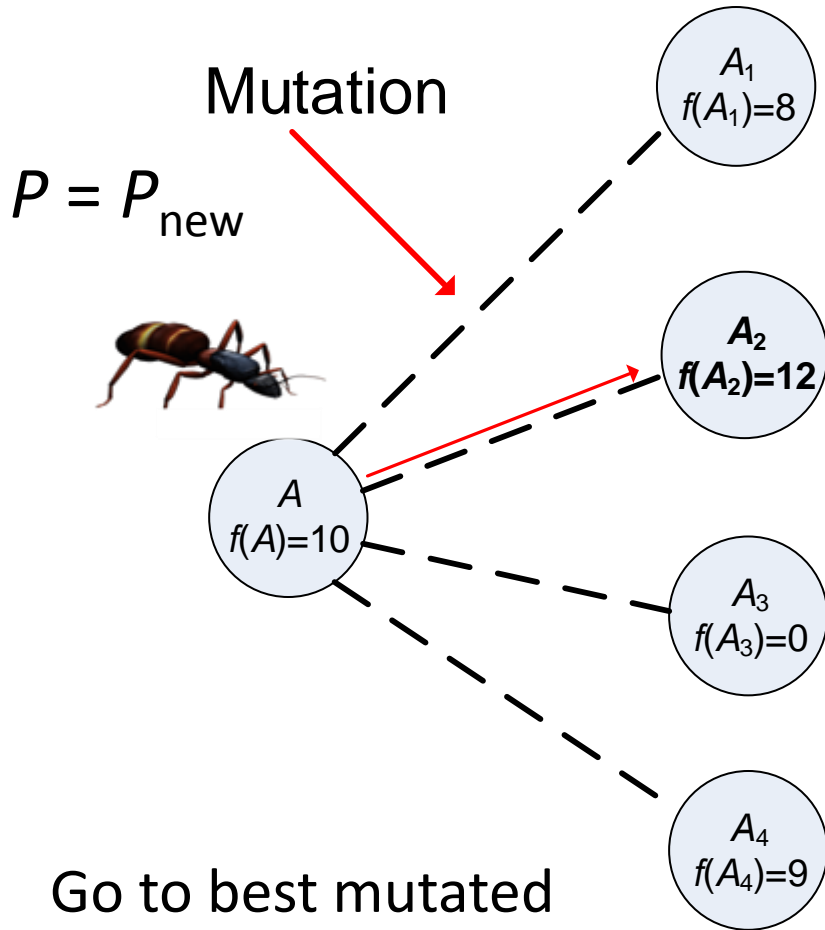


# Constructing ant solutions

- Use a colony of ants
- An ant is placed on a graph node
- Each ant has a limited number of steps
- On each step the ant moves to the next node

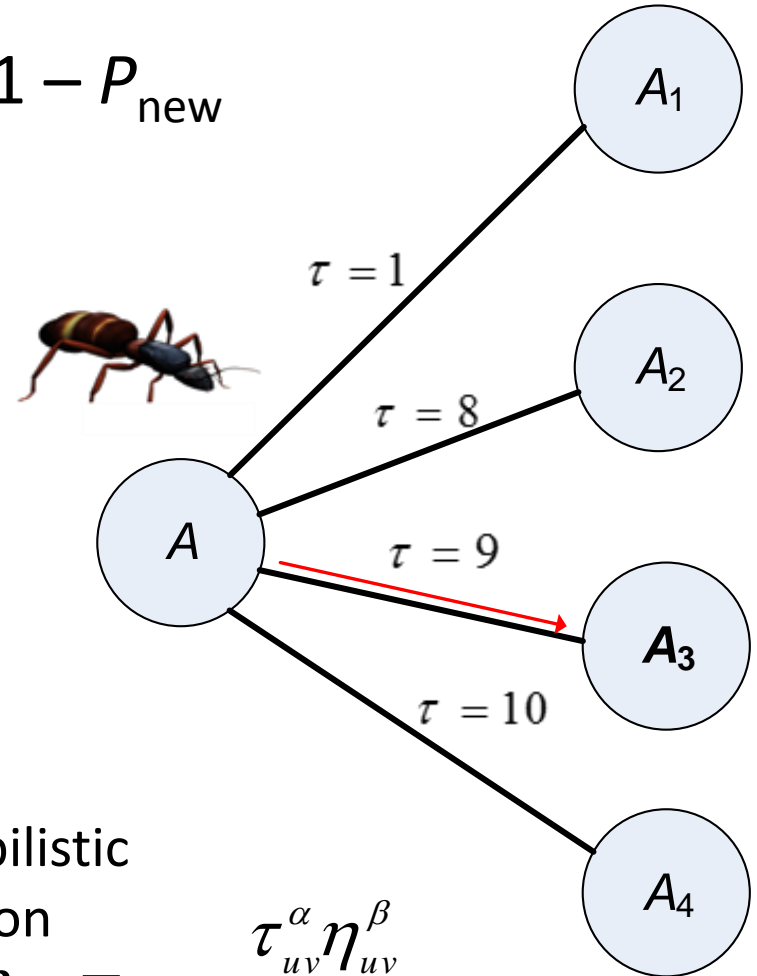


# Ant step: selecting the next node



Go to best mutated FSM

$$P = 1 - P_{\text{new}}$$



Probabilistic selection

$$P_{Av} = \frac{\tau_{uv}^\alpha \eta_{uv}^\beta}{\sum_{w \in \{A_1, A_2, A_3, A_4\}} \tau_{uw}^\alpha \eta_{uw}^\beta}$$

# Why parallel MuACO?

- Single-node MuACO is more efficient than GA for EFSM inference
  - Chivilikhin D., Ulyantsev V. MuACOsm - A New Mutation-Based Ant Colony Optimization Algorithm for Learning Finite-State Machines / In GECCO'13
  - Chivilikhin D., Ulyantsev V. Inferring Automata-Based Programs from Specification With Mutation-Based Ant Colony Optimization / In GECCO'14

# Parallel combinatorial optimization

- Randomized algorithms
- More exploration – higher chance of finding optimal solution
- Increase exploration using parallelism

# Parallel metaheuristics

- Evolutionary algorithms
  - Island scheme
  - Migration
  - MuACO doesn't have a population
- Ant Colony algorithms
  - Multiple colonies
  - This can work

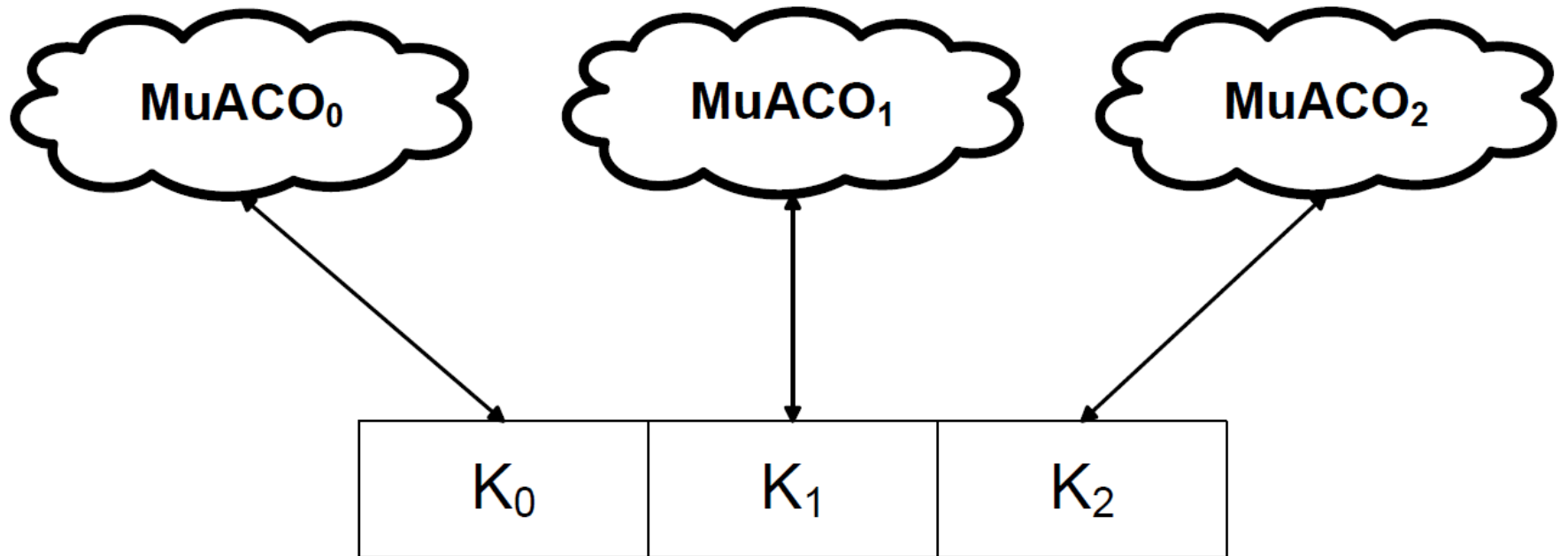
# Three parallel MuACO algorithms

1. Independent parallel MuACO
2. Shared best solutions
3. MuACO with crossover

# Independent parallel MuACO

- $m$  processors
- Generate  $m$  random initial solutions
- Start  $m$  MuACO algorithms
- Terminate when at least one finds optimal solution
- NO interaction between algorithms

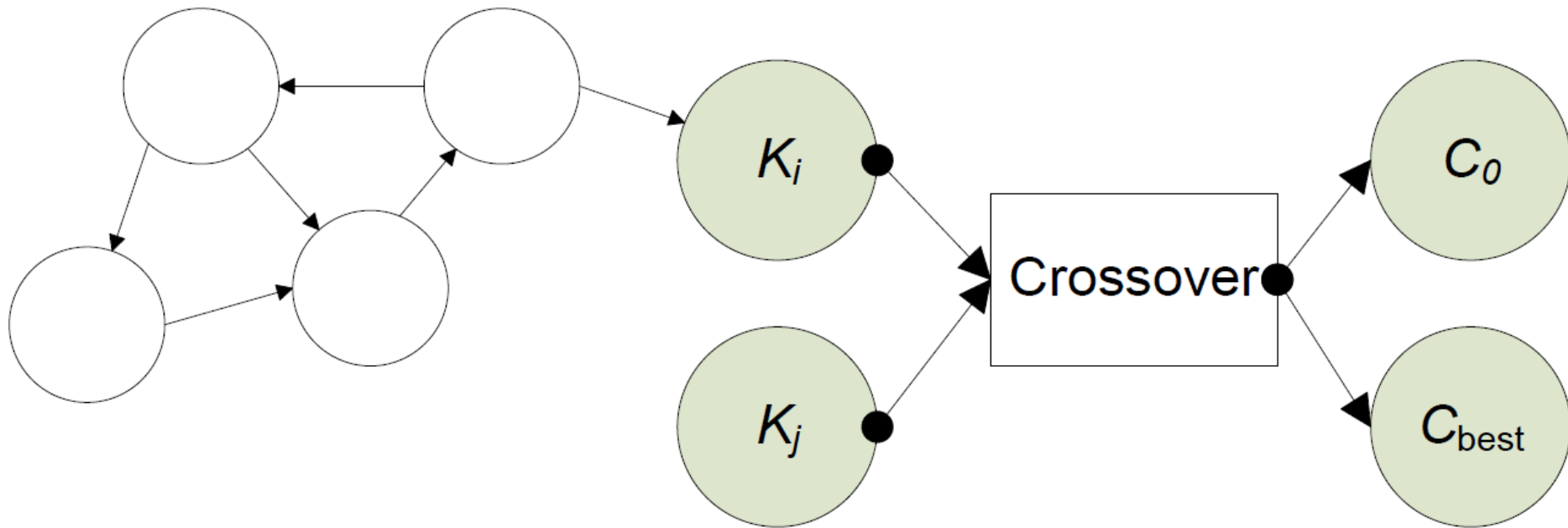
# Shared best solutions



- $i$ -th algorithm restarts with  $j$ -th algorithm's best solution



# MuACO with crossovers



Crossovers from: F. Tsarev and K. Egorov. Finite state machine induction using genetic algorithm based on testing and model checking. In GECCO'11 Companion Proc., pp.759–762, Dublin, Ireland, 2011.

# Other tested approaches

- Parallel fitness evaluation
- Different algorithm settings
- ...
- No good

# Learning EFSMs from scenarios and temporal properties

Input data:

- Number of states  $C$
- Set of test scenarios
- Set of temporal properties

**Goal: build an EFSM with  $C$  states compliant with scenarios and temporal properties**

# Scenarios and temporal properties

- Scenario
  - $T[x_1 \ \& \ x_2]/z_1, A[\text{true}], A[x_2 \ \& \ !x_1]/z_2, T[x_1]/z_3$
- Temporal properties – Linear temporal logic
  - $G(\text{wasEvent}(T) \Rightarrow \text{wasAction}(z_1))$

# Learning EFSMs: Fitness function

- Pass inputs to EFSM, record outputs
- Compare generated outputs with references
- Use verifier to check temporal properties
- Fitness = string similarity measure (edit distance) + verification part

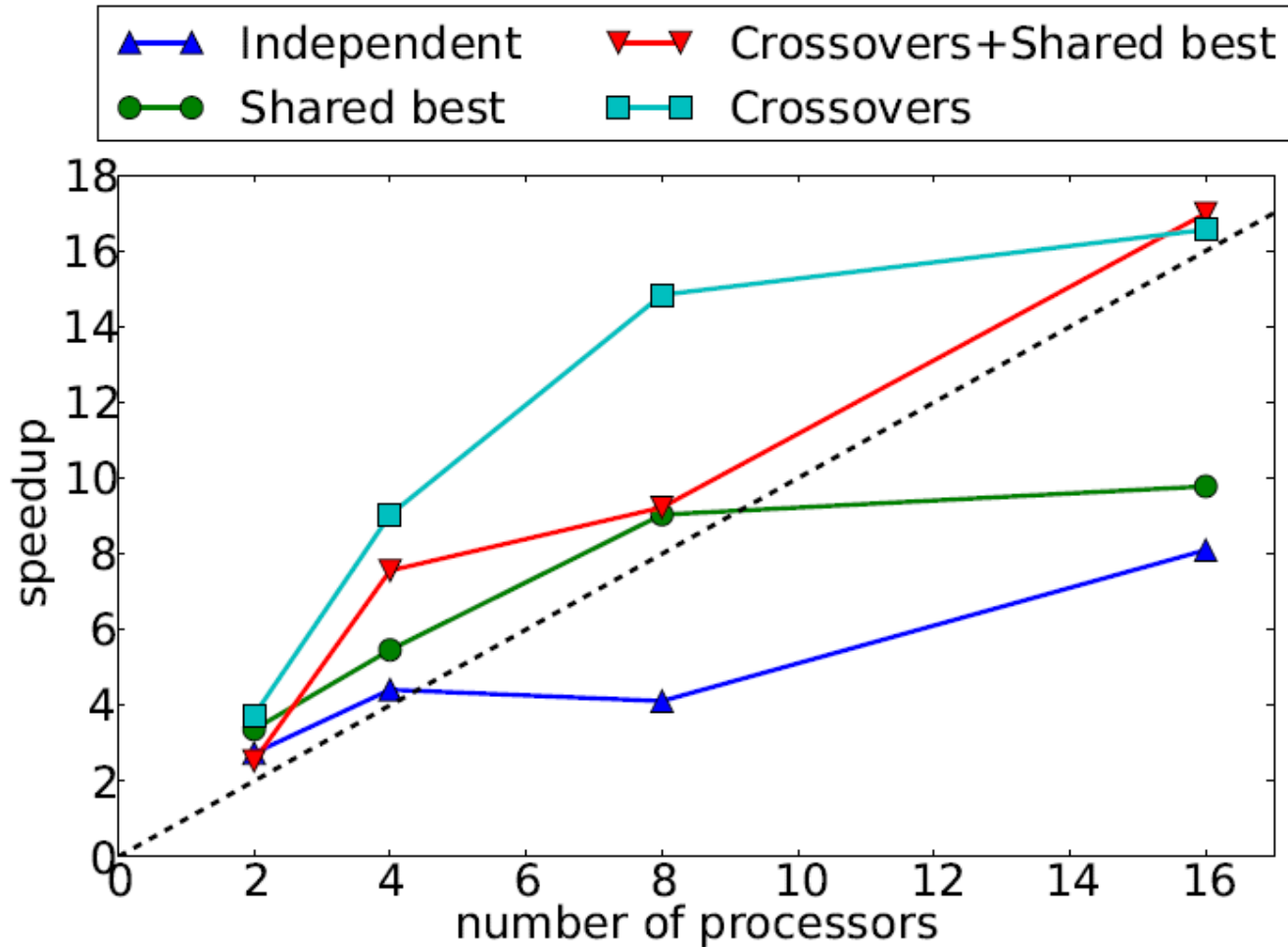
# Experimental setup

- 50 random EFSMs with 10 states
  - One input variable
  - Two input events
  - Two output actions
  - Sequence length up to 2
- 
- 24-core AMD Opteron 6234 2.4 GHz processor

# Compared algorithms

- Sequential MuACO
- Independent parallel MuACO
- Parallel MuACO + Shared best
- Parallel MuACO + Crossovers
- Parallel MuACO + Shared best + Crossovers
- Independent parallel GA

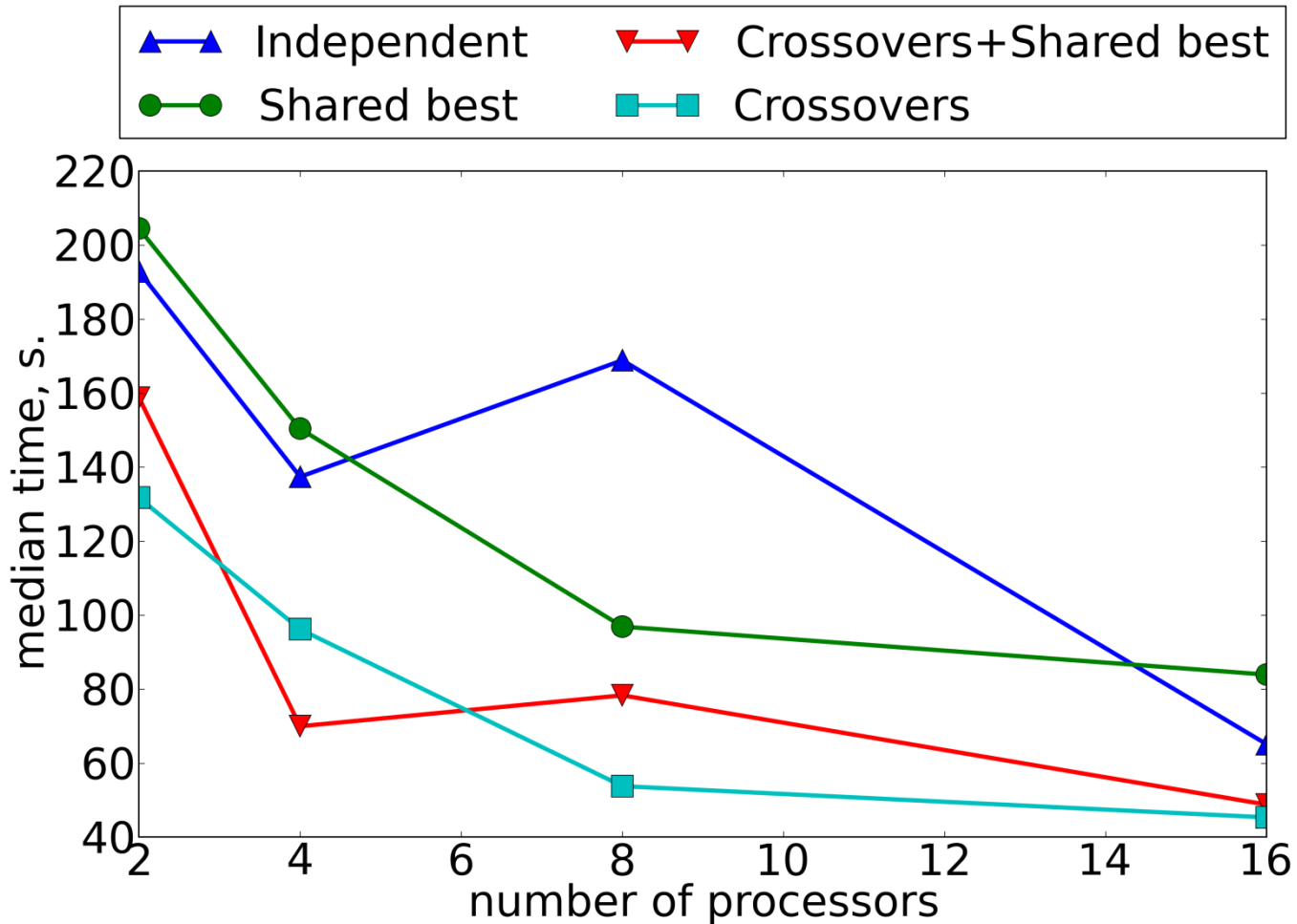
# Results: MuACO speedup



Sequential MuACO runtime = 1392 s.

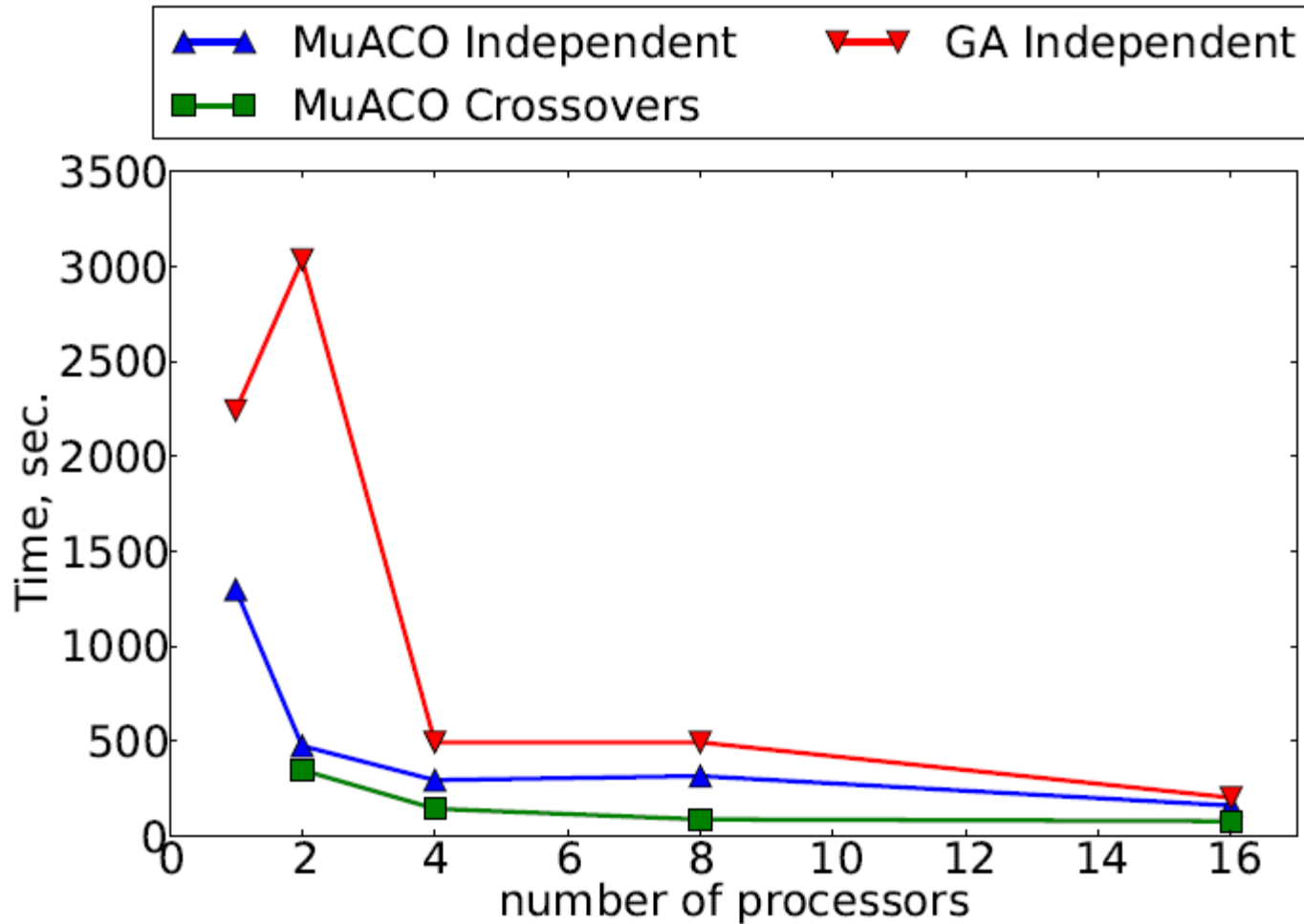


# Results: median time



EFSM Inference with Parallel  
ACO based Algorithms

# Results: comparison with GA



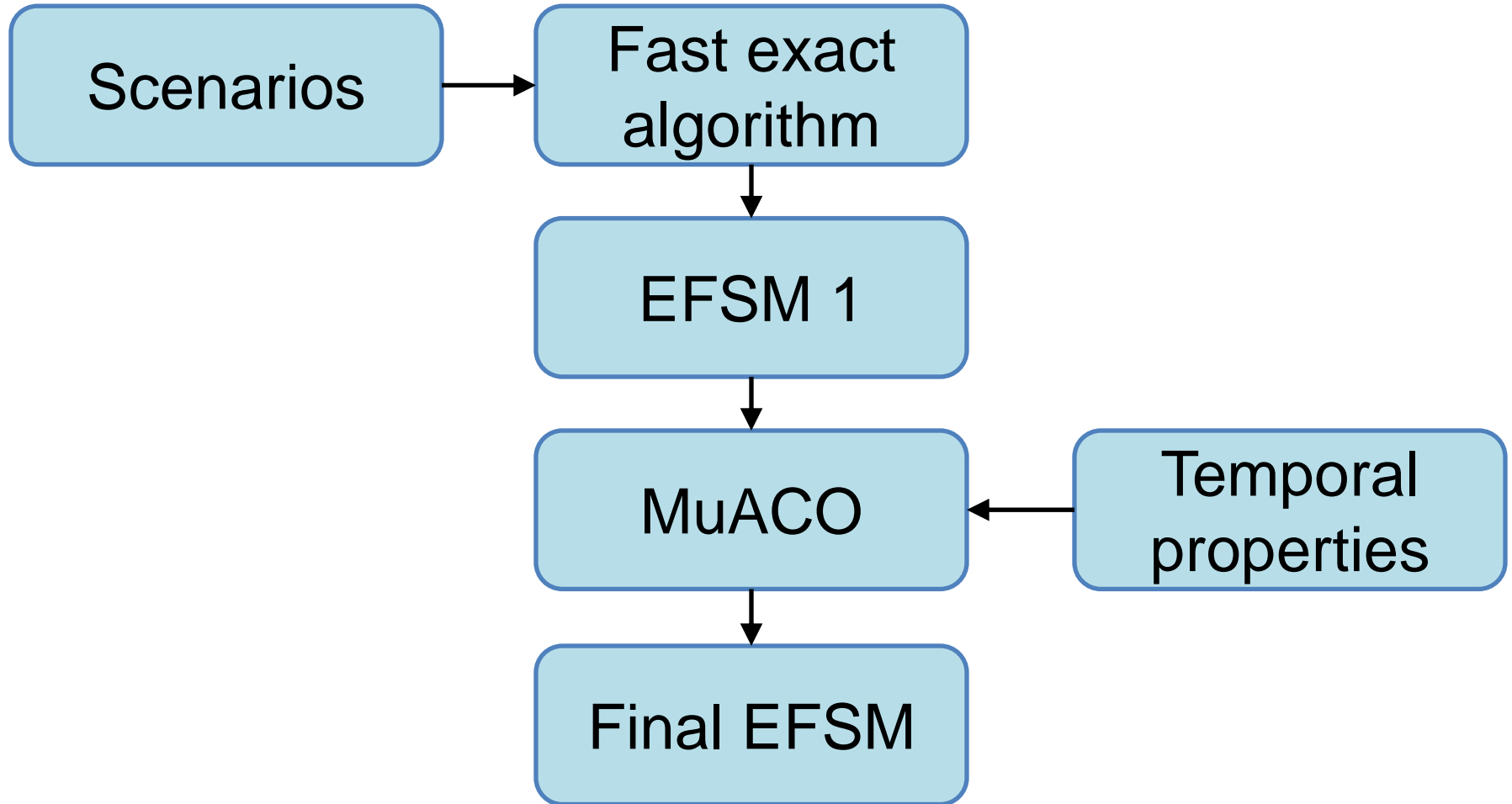
# Statistical significance

- Both “Crossovers” are significantly better than other algorithms
- Not significantly different from each other

# Combining exact and metaheuristic algorithms

- ICMLA'14: Combining Exact And Metaheuristic Techniques For Learning Extended Finite-State Machines From Test Scenarios and Temporal Properties (accepted)

# Combining exact and metaheuristic algorithms



# Combining exact and metaheuristic algorithms: results

	Crossovers	Exact + Crossovers
Mean time, s.	208	78
Median time, s.	73	28

# Conclusion

- Parallel EFSM inference algorithms are very efficient
- Parallel MuACO algorithms with crossover demonstrated best performance
- With super-linear speedup

# Future work

- Parallel MuACO-GA algorithm
- Experiments using more computational nodes
- More experiments with exact algorithms



# Acknowledgements

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# Thank you for your attention!

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