



Empirical Convergence Analysis Of Genetic Algorithm For Solving Unit Commitment Problem

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Introduction

■ Power system



Introduction

- Power system
- Unit Commitment problem?



Introduction

- Power system
- Unit Commitment problem?
- Motivation for an optimization approach



Introduction

- Power system
- Unit Commitment problem?
- Motivation for an optimization approach
- Techniques as MIP, MILP, LR, Benders
Decomposition, Dynamic Programming, ...



An Upper Bound on the Convergence Speed

Theorem

[1] Let the size of population of the GA be $n \geq 1$, coding length $l > 1$, mutation probability $0 < p_m \leq \frac{1}{2}$ and let $\{\vec{X}_t, t \geq 0\}$ be the Markov chain population, $\pi^{(t)}$ distribution of t^{th} generation of \vec{X}_t and π be the stationary distribution. Then it holds

$$\|\pi^{(k)} - \pi\| \leq (1 - (2p_m)^{nl})^k.$$



Convergence of Homogenous Algorithm

Theorem

[2] Let $a, b, c > 0$ be constants and i intensity perturbations of algorithm. If it holds

$$m > \frac{an + c(n-1)\Delta^{\otimes}}{\min(a, b/2, c\delta)}, \quad (1)$$

then

$$\forall x \in S^N : \quad \lim_{i \rightarrow \infty} \lim_{t \rightarrow \infty} P([X_t^i] \subset f^* | X_0^i = x) = 1.$$



Combination of Both Approaches

Idea, to get the best algorithm possible, is to set a sequence of parameters $\{(n_t, p_m(t)), t \geq\}$ that it holds $n_t < n_{t+1}$ and $p_m(t) > p_m(t + 1)$.

A Genetic algorithm set like this could be called a variable-structure GA [1].



Problem formulation

$$\min_{x_{i,t}^{type}} \left\{ \sum_{t=1}^T \sum_{i=1}^n (mp_{i,t} x_{i,t}^{type} + \max\{s_{i,t} - s_{i,t-1}, 0\} sc_i) \right\}$$

$$\sum_{i=1}^n x_{i,t}^{type} \geq PDP_t(\text{price}), \forall t \quad (2)$$

$$s_{i,t} = \begin{cases} 1, & \text{"if } x_{i,t}^{type} > 0, \\ 0, & \text{otherwise.} \end{cases}, \forall t, i \quad (3)$$

$$st_{i,t} = (-1)^{1-s_{i,t}} \sum 1_{\left\{ \begin{array}{l} l=[t-a,t+b] \wedge a,b \geq 0: \\ s_{i,t} = s_{i,\bar{t}} \forall \bar{t} \in l \wedge s_{i,t-a-1} = s_{i,t+b+1} = 1 - s_{i,t} \end{array} \right\}} \quad (4)$$

$$st_{i,t} \geq tup_i \vee st_{i,t} \leq -tdown_i, \forall t, i \quad (5)$$

$$x_{i,t} = xmax_{i,t} \quad (6)$$



Algorithm

- 1: $t = 0$
- 2: $P(t) = \text{SetInitialPopulation}(P)$



Algorithm

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- 3: Evaluate($P(t)$)
- 4: **while** not EndingCondition() **do**
- 5: $t+ = 1$
- 6: $P(t) = \text{Selection}(P(t - 1))$



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- 8: $P(t) = \text{Mutation}(P(t))$
- 9: Evaluate($P(t)$)
- 10: **end while**

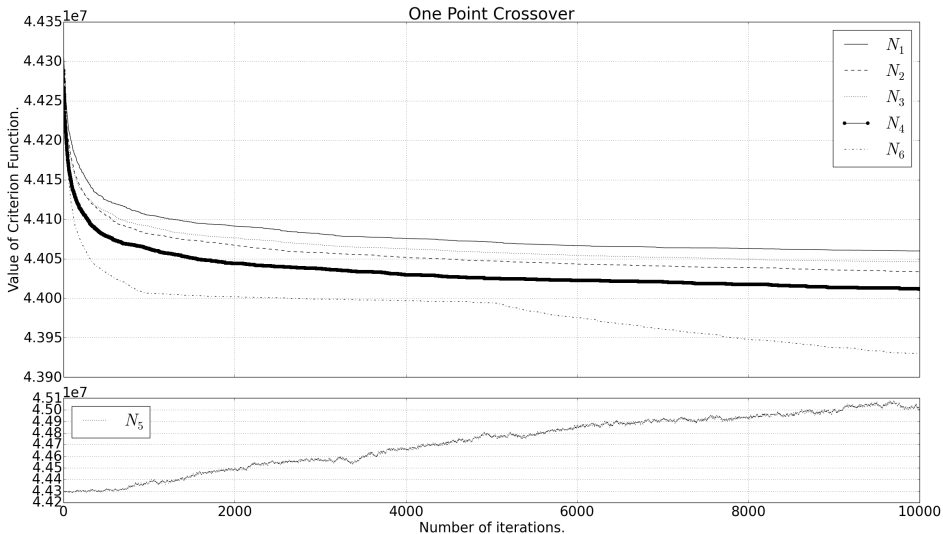
Results

Table 1. Parameter settings.

Parameters / Settings	N_1	N_2	N_3	N_4	N_5	N_6
Iterations	10,000	10,000	10,000	10,000	10,000	10,000
Population size	30	30	30	60	30	60
Elitism	4	4	4	4	0	4
Crossover	OPC	OPC	OPC	OPC	OPC	OPC
Crossover Probability	50%	75%	50%	50%	50%	vary
Mutation Probability						
- population	25%	25%	40%	25%	25%	vary
- individual	20%	20%	25%	20%	20%	vary

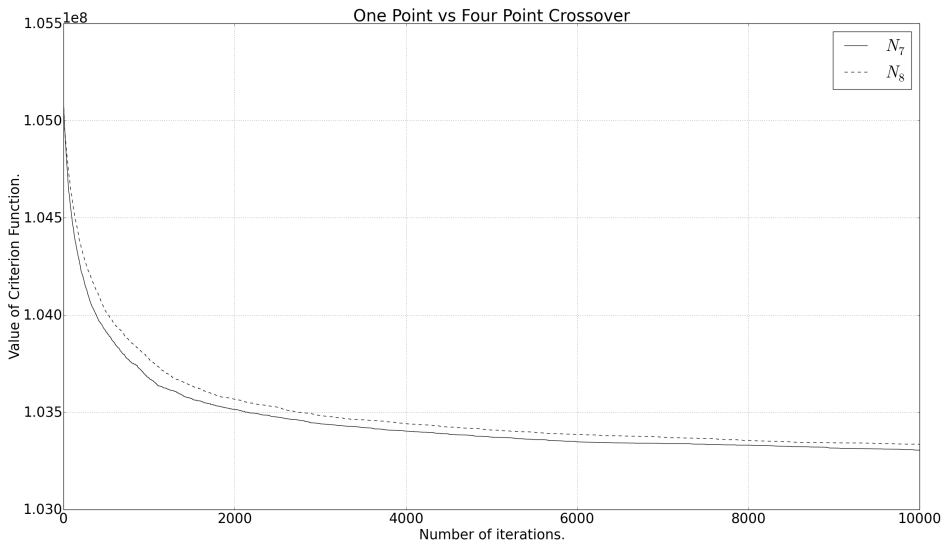


One-point crossover





Multi-point crossover



Appendix

Algorithm was implemented in the programming language Python.

- Numpy
- Cython
- Numba

On some parts of the code performance comparisons were made to implementations in other languages (R, Matlab and C#).



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